

Given a collection of damaged networks (made up of a set of damaged nodal components and a set of damaged line components), we can subdivide each network into different recovery zones. We can then write the zonal-scale optimization problem as the minimization of a set of objective function(s) (e.g., resilience metrics or cost) obtained by considering different priorities of the recovery zones.

The zonal-scale optimization problem is subject to physical and logical scheduling constraints for the recovery activities within each zone and service recovery constraints. Each set of these constraints entails a nested optimization. To schedule the recovery activities within each zone, we formulate a local-scale optimization problem whose objective is to minimize the recovery duration within the zone, while complying with physical and logical constraints to implement the recovery schedule. The objective of the service recovery optimization is to minimize a measure of discrepancy between the loss function estimates of the demand and supply measures through the recovery, while complying with the network-specific constraints, such as power balance equations for the power flow network (Glover et al. 2012). Further details about the recovery optimization can be found in Sharma et al. (2019b).

3.7.4.5 Resilience-Informed Infrastructure Recovery Example. The definition of an optimal recovery strategy is illustrated by modeling the performance of the electric power infrastructure in Shelby County, Tennessee. Shelby County has an approximately 1,000,000 population, and the region is subject to seismic hazards originating from New Madrid Seismic Zone (NMSZ). In this example, we consider a historical scenario earthquake with a moment magnitude of 7.7 and the epicenter at 35.93°N and 89.92°W. We model the spatial variation of the earthquake intensity measures by using a three-dimensional physics-based model to capture near-field effects [Guidotti, R., S. Tian, and P. Gardoni, "Simulation of seismic wave propagation in the Metro Memphis Statistical Area (MMSA)," in preparation] and ground motion prediction equations for far-field regions (Steelman et al. 2007).

The electrical power infrastructure in Shelby County is managed by the Memphis Light, Gas, and Water (MLGW) Division. The balancing authority of the region is the Tennessee Valley Authority (TVA) who also owns and operates the generators and transmission lines providing power to MLGW. The model for the power flow analysis is provided by Sharma et al. (2019a), building on the information provided in Shinozuka et al. (1998) and Birchfield et al. (2017). [Figure 3-21](#) shows the topology of the developed model for Shelby County (b) and Tennessee (a).

To model the physical recovery, we estimate the damage to the vulnerable components and develop a detailed recovery schedule for the

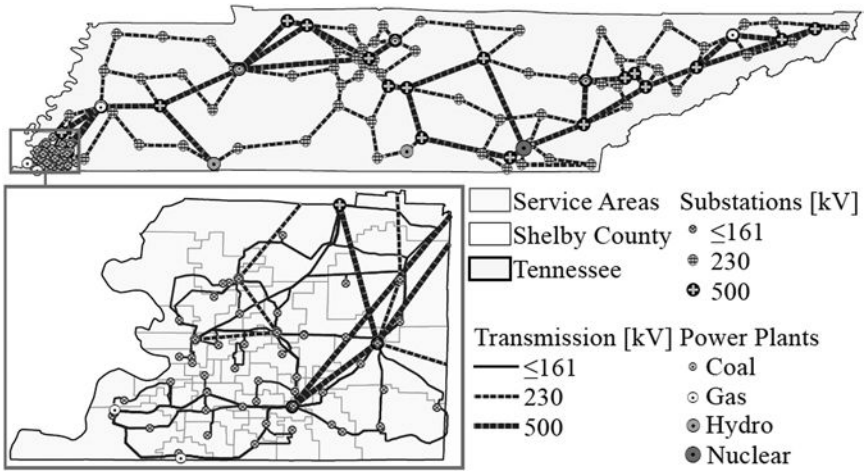


Figure 3-21. Electric power infrastructure in (a) Tennessee, and (b) Shelby County.

Source: Adapted from Sharma et al. (2019a).

repair or replacement of damaged components. Transformers, circuit breakers, and disconnect switches are vulnerable components to seismic excitations, which are all located in electric power substations. To develop the recovery schedule, we consider each substation and the corresponding service area as a single recovery zone. Given that two different agencies manage the electric power infrastructure inside and outside Shelby County, we define four different recovery projects as follows: (1) MLGW critical repairs, for nonfunctional substations in Shelby County; (2) MLGW noncritical repairs, for functional but damaged substations in Shelby County; (3) TVA critical repairs, for nonfunctional substations in Tennessee; and (4) TVA noncritical repairs, for functional but damaged substations in Tennessee. Further details of the recovery schedule can be found in Sharma et al. (2019a).

To model service recovery, we develop a structural network, $G^{[1]}$, and a power flow network, $G^{[2]}$. The structural capacity and demand measures are in terms of the hazard intensity measure, whereas the flow capacity and demand measures are in terms of the apparent power. The capacity of the flow network is dependent on the structural network. We account for this dependency in the modified flow capacity estimates and accordingly obtain the modified flow supply estimates by running power flow analyses. To summarize the overall service recovery, we define the aggregate performance measure $Q^{[agg]}(\tau) = \sum_{cell=1}^{n_{cell}} w_{cell} Q^{[2]}_{cell}(\tau)$, where cell is the service area of each substation; w_{cell} is a weight for the recovery cell that is

proportional to the power demand in the recovery cell; and $Q_{\text{cell}}^{[2]}(\tau)$ is the fraction of the power demand that is supplied in the recovery cell.

The scenario earthquake is estimated to cause damage to components in 17 of the 36 zones managed by MLGW, which require critical repairs. In this example, we use ρ_Q as the sole objective function in recovery optimization. To solve the optimization problem, we use a genetic algorithm (Goldberg 1989), whereas other algorithms could be used as well. Figure 3-22 shows the results for the service recovery in terms of $Q_{\text{cell}}^{[2]}(\tau)$, which is a binary-value quantity (dark gray is nonfunctional, and light gray is functional). Figure 3-22(a) shows the results according to the current recovery practice as defined in MLGW (2017), and Figure 3-22(b) shows the results according to the optimized recovery schedule. In Figure 3-22(a), we observe that $Q_{\text{cell}}^{[2]}(\tau)$ for some recovery cells fluctuates over time. This is because as the recovery advances, redistribution of loads on operating buses can result in voltage collapse. The optimized recovery results in $\rho_Q = 18.1$ h, compared with $\rho_Q = 26.5$ h for the current recovery practice (i.e., a 30.2% improvement). We can also observe that the improvement in $Q_{\text{cell}}^{[2]}(\tau)$ is not uniform across the region because some areas experience slower recovery than the others. This is because the focus of ρ_Q as the recovery objective, is on the recovery duration, thus not capturing the temporal and spatial variabilities in the recovery. Instead, one can use the formulation in Section 3.9.4 to define a multiobjective optimization problem that captures all desired resilience objectives in developing the recovery schedule.

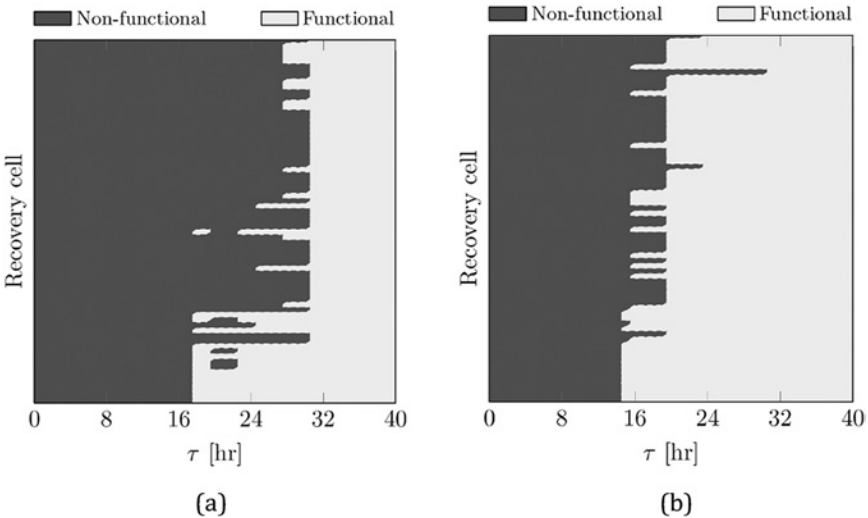


Figure 3-22. Predicted performance of the electric power infrastructure under (a) current recovery practice, and (b) optimized recovery schedule.

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